STANFORD UNIVERSITY

W.W. HANSEN EXPERIMENTAL PHYSICS LABORATORY GRAVITY PROBE B, RELATIVITY GYROSCOPE EXPERIMENT STANFORD, CALIFORNIA 94305-4085



ROOM-TEMPERATURE TEST OF CAGING SYSTEM IN PROBE C

GP-B SCIENCE MISSION PROCEDURE P0536 Rev-A

September 11, 2000

PREPARED		
	R. Brumley, Gyroscope RE	Date
APPROVED	J. Mester, Caging System RE	Date
APPROVED	C. Gray, Gyroscope Verification	Date
APPROVED	D. Ross, Quality Assurance and Safety	Date
APPROVED	B. Muhlfelder, Technical Manager	Date

REVISION HISTORY

Rev	Date	Comments
-	07/11/99	
A	09/11/00	Change procedure to incorporate minor redlines from the previous run. Main structure of the procedure has not been changed.

1. SCOPE

This procedure is intended to be used to verify the functionality of the caging system as part of the room-temperature checkout of Probe C prior to the cryogenic acceptance testing. It may be used at other stages of probe acceptance testing if so desired. This procedure is only intended to verify basic functionality of the system (i.e. that the gyroscope cages and uncages). It does not seek to measure any basic parameters of the caging process. Note that the DDC must be installed per procedure P0481 before performing this procedure.

2. REFERENCES

2.1 Plans and Procedures

P0481 Levitation of Gyroscopes in Probe C
P0505 RT Spinup of Gyroscopes in Probe C
P0410 Pumpdown and leak check

3. GENERAL REQUIREMENTS

3.1 Environmental Requirements

3.1.1 Cleanliness

This procedure takes place in the Class 1000 cleanroom in the HEPL building. Minimum protective garments for personnel working in the clean rooms shall be the standard Tyvek clean room apparel. All activities taking place within this room must be in accordance with the guidelines established by the cleanroom manager.

3.1.2 Particulate Contamination

All connectors shall be inspected and verified free of particulate contamination before they are mated to Probe C. It is also desirable to keep the probe in general clean and free of particulate contamination.

Note: The caging lines have an I.D. of 5 milli-inches. It is therefore very easy to clog the lines should any contamination be present. Great care must be taken to ensure that no particles get into the caging lines.

3.1.3 Magnetic Contamination

This procedure takes place after the vacuum can is sealed, making the experiment much less sensitive to magnetic contamination. However, great care shall still be taken to avoid cross contamination between any magnetic (e.g. steel) item and the probe, particularly on the probe's "cold" end. Therefore no magnetic items may be used in the immediate vicinity of the "cold" end of the probe.

3.2 Test Personnel

3.2.1 Test Director

The test director for this procedure shall be Robert Brumley, or his appointed replacement.

3.2.2 Personnel

The following personnel have received the training necessary to perform this procedure.

- David Hipkins
- Bruce Clarke
- Chris Gray
- Robert Brumley
- Dr. John Mester
- Dr. Sasha Buchman

See section 3.4 for details on the requirements for Quality Assurance notification and witnessing of this procedure.

3.2.3 Minimum Personnel

No activity shall be performed on the science mission probe without at least two people in the room, i.e. at least one person to perform the procedure and one person to observe the procedure.

3.3 Safety

3.3.1 Hardware Safety -- General

It is important to be cognizant at all times of the position of the probe. Be extremely careful not to accidentally bump into the probe. If any connector does not connect smoothly and securely, do not try to force it. Instead, remove the connector and inspect it to find the reason for the difficulty. Great care must be taken at all times during the performance of this procedure.

3.3.2 Electrostatic Discharge

Grounded wrist straps shall be worn at all times when mating or demating to an electrical connector on Probe C.

3.3.3 Personnel Safety

All operations shall take place according to Stanford University safety guidelines. Any person observing a situation which they deem unsafe shall report the fact immediately to the test director. The Quality Assurance representative shall be responsible for monitoring that all activities are performed in a safe manner.

3.4 Quality Assurance

- Stanford QA must be notified at least 24 hours before beginning this procedure.
- ONR QA must be notified at least 24 hours before beginning this procedure.
- D. Ross (or her designate) must be present to monitor the completion of this procedure.

This procedure shall be conducted on a formal basis to its latest approved and released version. The QA Program Engineer shall be notified of the start of this procedure. A Quality Assurance representative designated by D. Ross shall review any discrepancy noted during test. Redlines shall be approved by the QA representative. The QA representative will nominally be Russ Leese. Upon completion of this procedure, the QA Program Engineer, D. Ross or R. Leese, shall certify his or her concurrence that the effort was performed and accomplished in accordance with the prescribed instructions by signing and dating the appropriate approval line at the end of the procedure.

3.5 Red-Line Authority

Authority to red-line (make minor chances during execution) this procedure is given to the qualified personnel listed in section 3.2.2. All redlines must be approved by the QA representative. In addition, approval by the Hardware Manager shall be required if, in the judgement of the test director or the QA representative, experiment functionality may be affected.

3.6 Electrical Connections

When mating to any flight connector, the following items are required:

- A grounded ESD strap must be worn by any person handling a connector on Probe C
- Inspect both connectors being mated to ensure that there are no particles that might interfere with the mate.

• Each mate and demate of flight connectors must be logged in that connector's mate/demate log sheet. Note that these log sheets have already been started for all suspension lines.

4. REQUIRED EQUIPMENT

4.1 Flight Hardware

• Probe C assembly with vacuum can installed, no sunshade.

4.2 Ground Support Equipment

The following equipment is necessary to perform these tests.

Item	Quantity
GSE plumbing assembly for caging	1
Bottle of ultra-pure He	1
Gaskets for VCR fittings (connector savers for flight gammah connections)	3
Digital Multimeter capable of reading resistances $>$ 200 M Ω .	1
Model:	
S/N:	
DDC-Probe C Interface Box	1
DDC Suspension System	1 / gyro testing

4.3 Software

No software is necessary for this procedure.

4.4 Tools and Miscellaneous

Fluke meters and capacitance meters shall be readily available should the need to trouble shoot arise.

5. GUIDELINES FOR OPERATIONS

- This procedure may be completed with the probe either at atmospheric pressure or in high vacuum.
- This procedure should be completed for each gyroscope in the probe.
- Note that the DDC must be installed per P0481 before performing this procedure.
- Gyroscopes 1 and 2 can be tested separately
- Note that the same line feeds both gyroscopes #3 and #4. Therefore both gyroscopes cage at the same time. However, there are two valves that feed this one line. Both of these valves need to be checked.
- This procedure leaves the option for either a full cage (160 psi) or a partial cage "touch test" (~40 psi)

6.	INITIAL SETUP	
6.1	Enter the following data:	
	Start Date:	
	Start Time:	
	Gyroscope(s) #:	
	Note: Gyroscopes 3 and 4 are automatically caged at the same time.	
6.2	Assemble all equipment on the Equipment list in Section 4	
6.3	Turn on and prepare the leak detector for test. This should be done in accordance with its user manual.	
6.4	Purge the caging GSE for at least 5 minutes by opening V1, V2, V3, V5, V6 and the metering valve. V4 (the vent valve) should be closed.	
6.5	Set the regulator on the He supply to 165 psid.	
	Note: One should not exceed 185 psi on the caging assembly. Since the probe will be evacuated, 185 psi on the caging assembly = 185 – 14.7 ~ 170 psi on a gauge. Therefore the regulator on the He supply is set to 165 to provide some safety margin.	
6.6	Close the regulator on the caging GSE enough so that a very light flow of He is still present.	
6.7	Connect the GSE plumbing to probe C and the leak detector per Figure 1. Note that Figure 1 contains the proper valve designation. Record here:	

P0536 Rev. A September 11, 2000

6.8	Line Designation = Set the valves to the					
	(Open means gas of flow through the v	an flow through the valve, Closed means gas can not alve)				
	V1 ← Open					
	V2 ← Open					
	V3 ← Open					
	V4 ← Closed					
	V5 ← Open					
	V6 ← Open					
	V7 ← Open					
	V8 ← Closed					
	Metering Valve	⊨ Closed				
	GSE regulator	= Closed				
	He bottle regulator	□ Open at 165 psi				
6.9	Prepare to open the	valve on the caging line of Probe C.				
6.10	To be completed if	caging lines are currently under vacuum				
	manual. Pump on	ctor to test mode per the instructions in its user the caging assembly until the base pressure goes en the relevant caging valve on the probe. Go to step				
6.11	To be completed if	caging lines are currently at atmosphere				
	Open the relevant	Open the relevant caging valve on the probe.				
	the leak detector. 'desire to leak chec	representation pump on the caging line and GSE with This step need only be performed if (a) there is a the portion of the caging lines outside the vacuum red to eliminate any N2 in the lines prior to a				

P0536 Rev. A September 11, 2000

	Check if line was pumped on:
6.12	OPTIONAL CHECK FOR CAGING LINE TO WELL LEAKS
	If the lines are being pumped on with the leak detector according to 6.10 or the optional component of 6.11, it is now possible to perform a leak check on the portions of the caging lines that are outside the vacuum can. Record Results in Table 1. Check if done:

TABLE 1 (OPTIONAL): CAGING LINE LEAKAGE RATE CHECK (Caging Line to Well Leaks)

Caging Line (CG
---------------	----

Time	Port Pressure	He Rate	Notes

TABLE 1 (OPTIONAL): CAGING LINE LEAKAGE RATE CHECK (Caging Line to Well Leaks)

Time	Port Pressure	He Rate	Notes

6.12	Isolate the leak det	ector by closing	V7.		
6.13	Vent the leak detec	ctor according th	ne instructions in	its user manual.	
6.14	system (LTV). The lines which sit inside in the can when the	is allows a leak de the vacuum of lines are presso	check of the por can (by monitori urized for the ca	ng the rate of He rise	
	Check if done:				
6.15	The system is now	ready to begin 1	pressurization of	the caging line.	
7.	GYROSCOPE CA	AGING VERIE	FICATION		
7.1	Verify that the DD per P0481 Section	•	nnected to the pro	obe. If not, connect	
7.2	If not already done ground plane connections a	ection for the gy		nnector saver to the est. For reference,	
	Gyroscope #1: CC	518			
	Gyroscope #2: CC	328			
	Gyroscope #3: CC	38			
	Gyroscope #4: CC	3 48			
	Note that static proprocedure.	tection wrist ba	nds must be wor	n during this	
7.3	Connect the Electro	ometer to the gr	ound plane conn	ection per Figure 2.	
7.4	Connect the other of identical to the potential			nd (which should be ntial).	
7.5	Record the initial ((microinches). No gyroscopes simulta	te that the secon	nd line is only to	the DDC be used if caging two	
	X = Y	<i>T</i> =	Z =	Gyro #	
	X = Y	<u></u>	Z =	Gyro #	
7.6	Verify that the valv	es are in the fol	llowing state:		
	V1 ← Open				
	-		-		
	$V2 \leftarrow Onen$				

	V3 ←	Open				
	V4 ←	Closed				
	V5 ←	Open				
	V6 ⇐	Open				
	V7 ←	Closed				
	V8 ⇐	Closed				
	Metering	Valve ←	Closed			
	GSE regu	lator ←	Open at 160 psi	40 for partial cage)	_	
	He bottle	regulator ←	Open at 165 psi	45 for partial cage)	_	
	Caging Va	alve on Probe	← Already oper	ı <u> </u>		
7.7	Open the	metering valv	e slowly.			
7.8	Gradually increase the pressure regulated by the caging GSE's regulator until the gyroscope cages. Record the process in the following table. The gyroscope is caged when the resistance indicated on the ohmmeter goes from >1 G Ω to ~100 M Ω and when the rotor has stopped moving on the DDC position readout.					
7.9	Close the	e metering valv	re and V3			
7.10	Note that		e is only to be used	on the DDC (microinches). if caging two gyroscopes		
	X =	Y = _	Z=	Gyro #		
	X =	Y = _	Z=	Gyro #		
7.11	Venting	Line to Atmos	phere			
	complete	ed as the final c	-	method if it is not being ing line prior to insertion int	co.	
	Vent the has left to	• •	g V4. Close V4 as	soon as the high-pressure Ho	e 	
7.12	Leaving	Line in Vacuu	ım.			
	This step	leaves the line	e in vacuum. It sho	uld be performed whenever	it	

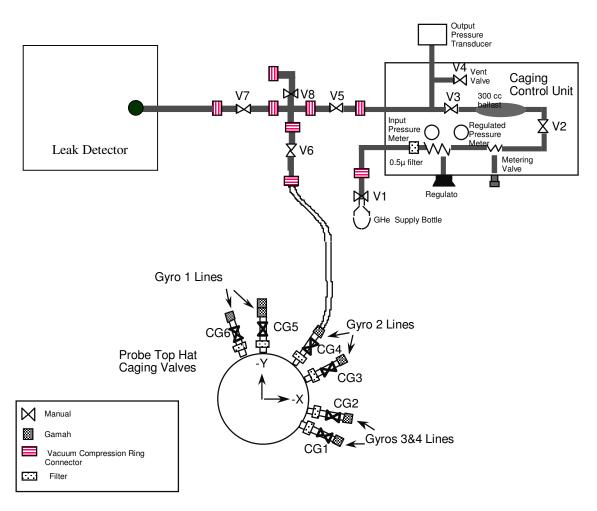
P0536 Rev. A September 11, 2000

		ry to leave the line re insertion).	without any air	n it (e.g. prior to low-	
	the space b		etector and V7 is	he leak detector to test. As being pumped down, open	
7.12	Close the C	CG valve on the pr	robe for the cagir	ng line being tested.	
7.13	Record the	e final (uncaged) re	esistance:		
	R =		_		
7.14	Record the final (uncaged) position below (the second line is to be used if two gyroscopes are being caged at once).				
	X =	Y =	Z=	Gyro #	
	X =	Y =	Z=	Gyro #	
7.13	Remove th	ne caging GSE from	m the probe.		
7.14	Replace th	e cap on the valve	of the caging lin	e in the probe	

RECORD OF CAGING CHECK

Gyroscope #	Caging Valve CG

(psid) [X Y Z] microinches (e.g. Caging Leak Rate)	Pressure	Resistance	Gyroscope Position [X Y Z] microinches	Notes
	(psia)		[A 1 Z] inicronicies	(e.g. Caging Leak Rate)
1				



Caging GSE Plumbing Schematic - not to scale

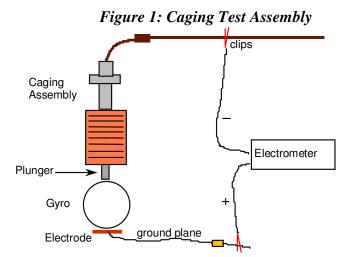


Figure 2: Schematic for Ground Plane Resistance Check

8. PROCEDURE COMPLETION

Record completion of this procedure in the traveler, as appropriate.

Record any abnormalities or deviations from this procedure in the D-Log. If the QA representative decides it is appropriate, open a Discrepancy Report to document the event.

This test has been completed according to the procedure contained herein. All redlines used have been integrated into this document.

Test Director:	
(print)	(sign)
(optional)	
Test Engineer:	
(print)	(sign)
(optional)	
Test Engineer:	
(print)	(sign)
QA Representative:	
(print)	(sign)